





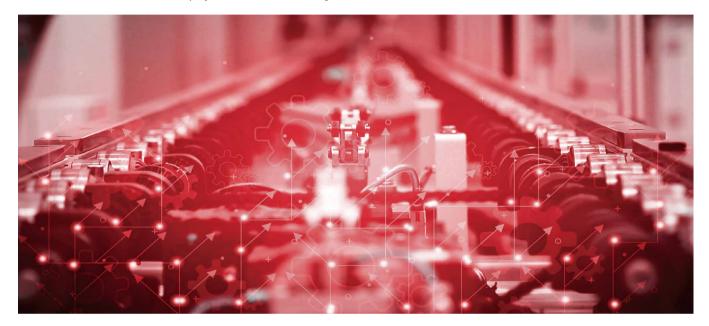




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# **Company Profile**

We are a technological innovation enterprise born out of Zhejiang University. It is a national high-tech enterprise, the fourth batch of "small giant" enterprises of the Ministry of Industry and Information Technology, and a special enterprise of Zhejiang Province. Our company has more than 180 employees, including 4 overseas talents, 4 professors, and 2 associate professors. There are also 12 doctors, and more than 86% of employees with a bachelor degree or above.



We are committed to intelligent manufacturing, high-end equipment, intelligent sensing, intelligent detection, military industry and other fields. Most of our company's products are independently researched and developed, and the market share ranks in the forefront of the domestic industry. A variety of equipment is the first set in China, which breaks the long-term monopoly of foreign companies.

We are a national high-tech enterprise integrating scientific research, product development, engineering design, and technical consulting. Besides, the company has obtained 45 invention patents, 29 utility model patents, 10 software copyrights, and 4 registered trademarks.

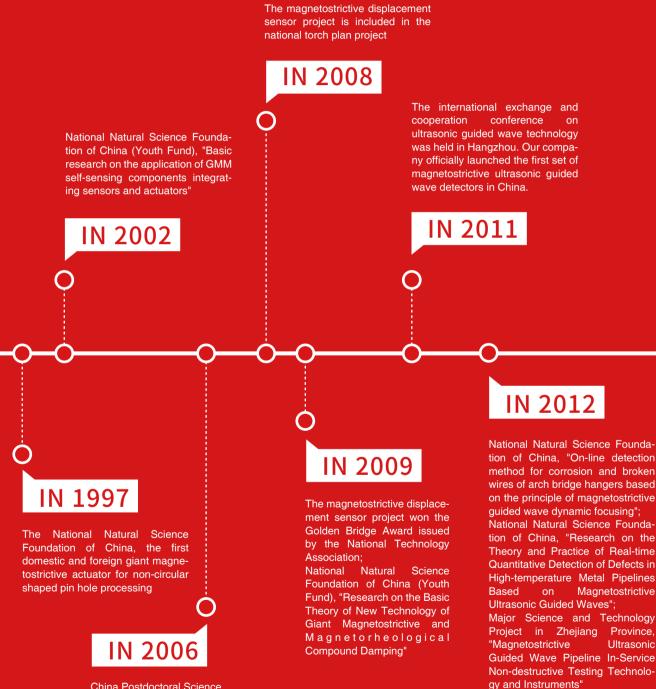
Taking "Created in China, Create China" as our ideal, we are committed to building a century-old national brand. Our development goal is to become a well-known leading technology and strength-based enterprise in China's high-end equipment and intelligent inspection industries.

# **Honorary Qualification**





## **TEC Magnetostriction Development**

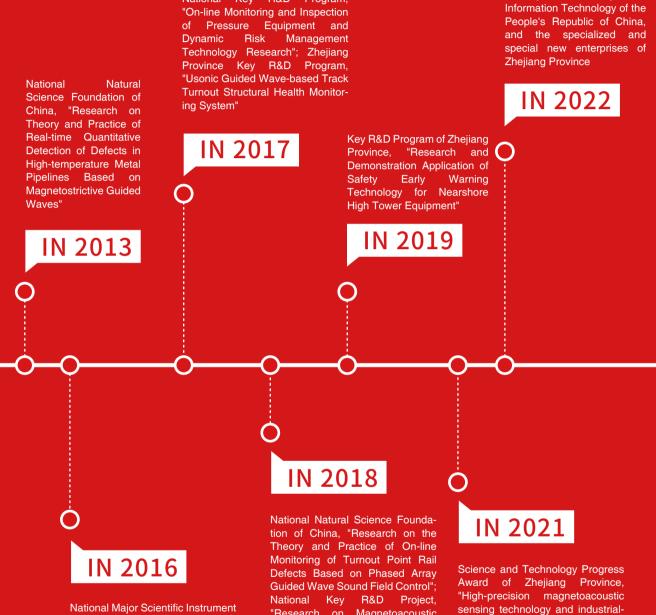


China Postdoctoral Science First-Class Funding Project

The fourth batch of "Small Giant" enterprises of the Ministry of Industry and

ization application of important

components".



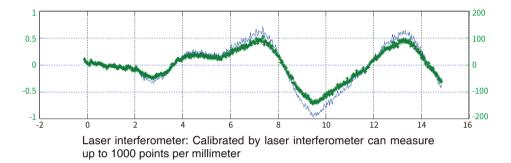
National Key R&D Program,

National Major Scientific Instrument and Equipment Development Project, "R&D of Rail Broken Monitoring Equipment and Testing Network in Key Sections"

National Key R&D Project, "Research on Magnetoacoustic Compound Monitoring and Detection Technology for Typical Pressure-bearing Special Equipment Damage"

## **Quality Assurance**

After years of experience and precipitation, TEC magnetostrictive displacement sensor has built a modern, automatic and standardized production line, which ensures the reliability, stability and consistency of products. Before the new series of products are put into the market, they must pass EMC, vibration, impact, high and low temperature tests. Sensors need to go through signal verification before and after each manufacturing process. After assembly, they are tested and screened one by one. Finally, they pass the calibration and linearity detection of laser interferometer, and the detection results are uploaded to the database for subsequent tracking of products



## Parts Test

### Electro Magnetic Compatibility (EMC)

| Electrostatic discharge immunity                            | (GB/T17626.2, IDT IEC61000-4-2) |
|---|---------------------------------|
| Radiation immunity of radio frequency electromagnetic field | (GB/T17626.3, IDT IEC61000-4-3) |
| Immunity of electrical<br>fast transient                    | (GB/T17626.4, IDT IEC61000-4-4) |
| Surge (shock) immunity                                      | (GB/T17626.5, IDT IEC61000-4-5) |
| RF field induced conducted disturbance immunity             | (GB/T17626.6, IDT IEC61000-4-6) |
| Power frequency magnetic field immunity                     | (GB/T17626.8, IDT IEC61000-4-8) |

### **Temperature Test**

| Low temperature       | (GB/T2423.1, IDT IEC60068-2-1)   |
|-----------------------|----------------------------------|
| High temperature      | (GB/T2423.2, IDT IEC60068-2-2)   |
| Constant damp heat    | (GB/T2423.3, IDT IEC60068-2-78)  |
| Alternating damp heat | (GB/T2423.4, IDT IEC60068-2-30)  |
| Temperature change    | (GB/T2423.22, IDT IEC60068-2-14) |

### Other Tests

| Explosion-proof test                            | (GB3836.1, IDT IEC60079-0)   |
|---|------------------------------|
| Explosion-proof test                            | (GB3836.2, IDT IEC60079-1)   |
| Explosion-proof test                            | (GB3836.4, IDT IEC60079-11)  |
| Insulation resistance, insula-<br>tion strength | (GB/T15479)                  |
| Impact test                                     | (GB/T2423.5, IDT IEC68-2-27) |
| Free drop test                                  | (GB/T2423.8, IDT IEC68-2-32) |
| Vibration test                                  | (GB/T2423.10, IDT IEC68-2-6) |
| Highly accelerated life test                    | ( HALT)                      |
| Enclosure protection test                       | (GB/T4208-2017)              |

## **Technical Terminology**

### Absolute position

The output of the sensor is relative to a fixed reference point, which does not need to be reset when power supply is restored after power failure; this position is an absolute position. However the general incremental sensor, such as incremental encoder and incremental grating ruler, which needs to find the reference point again.

#### Environmental conditions

For normal Operating conditionsof displacement sensors, the industry has the following standards:

- a) Temperature:25°C (±10°C)
- b) Relative humidity: 90% or less

Generally, the environment for calibrating and testing sensors is more stringent than the standard requirements.

#### Measuring range

For the sensor, the physical quantity to be measured is indicated by upper and lower limits. The measurement range is the full scale of motion.

#### Full scale

Full scale (abbreviated as "F.S") (see measuring range).

### Resolution

Refers to the minimum amount of sensor output that can be distinguished. The highest resolution of TEC magnetostrictive displacement sensor can reach1µm.

#### Nonlinearity

Nonlinearity is the absolute deviation as a percentage of the Stroke length length. In a magnetostrictive sensor, this change is caused by the difference in the propagation velocity of the return signal propagating in the waveguide medium.

#### Non-contact

Magnetostrictive displacement sensor uses non-contact magnetic induction technology to measure position. Non-contact measurement does not exist mechanical wear and mechanical vibration, which improves the reliability and service life of the sensor.

### Temperature coefficient

The temperature coefficient unit is ppm/°C (one millionth per degree Celsius). It refers that the ambient temperature changes by 1 degree Celsius, the amount of change in the position value output by the sensor.

### Update time

The time interval between two measurements made by the sensor. The larger the range of the sensor, the longer the update time required.

### Multiple position measurement

Measure the position of multiple magnet rings on the sensor stroke shaft or guide rail at the same time.

### Precision

The difference between the indicated measured value and the true value can be calculated from the root mean square of the nonlinear deviation, repeatability, and hysteresis.

#### Hysteresis

The difference in displayed position when reaching the same point from opposite directions along the length of stroke (Note: Magnetostrictive displacement sensors have very little hysteresis and are therefore negligible in most applications).

### Drift

Drift refers to the change of output signal or output value under the influence of surrounding environment, such as time or temperature. Please refer to "preheating period" and "temperature coefficient" at the same time.

#### Shell protection class

The IP (Ingress Prection) standard for shell intrusion protection issued by the International Electrotechnical Commission. For specific IP standard instructions, please refer to the official website of IEC. The optional protection levels of sensors are IP65, IP67 and IP68.

### Preheating period

The time required for the sensor to be energized until the output is stable, this deviation can be seen from the calibration curve of the sensor.

#### Load impedance

The impedance when the external circuit is connected to the output end of the sensor.

#### Repetition accuracy

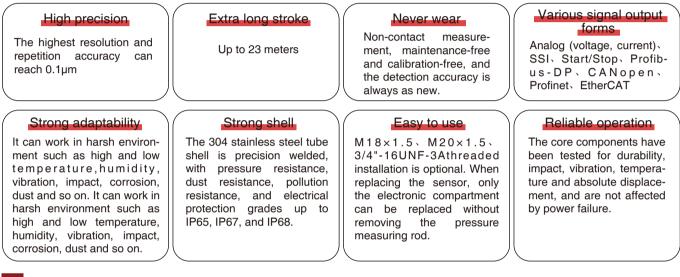
The difference in sensor output when the magnet repeatedly reaches the same position from the same direction when measured along the stroke.

# **Technical Characteristics**

### C C Product Introduction

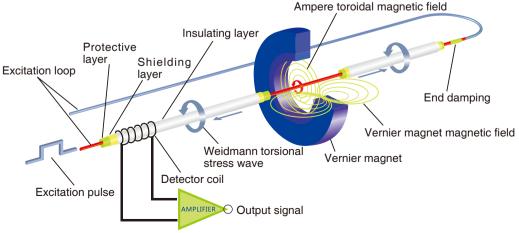
TEC magnetostrictive displacement sensor is a new generation of linear displacement sensor independently developed by Zheda Jingyi. It can provide users with real-time, reliable, accurate and continuous linear displacement signals under harsh working environment, and is widely used in metallurgical equipment, wind power equipment, construction machinery, rubber machinery, port machinery, energy and other industrial automation fields.

### C C Product Characteristics



### G g Working Principle

The detection mechanism of the magnetostrictive displacement sensor is based on the "Weidmann effect" between the magnetostrictive waveguide wire and the vernier magnet which is the core detection element of the sensor. The excitation module in the sensor electronic bin will apply a query pulse at both ends of the loop where the sensitive detection element (magnetostrictive waveguide wire) is located, and the pulse forms a circumferential ampere annular magnetic field around the waveguide wire at speed of light. The magnetic field is coupled with the permanent magnet magnetic field at the position of the vernier magnet, and a "Weidmann effect" torsional stress wave is formed on the surface of the waveguide wire. The torsional wave transmitted to the end is absorbed by the damping device, and the signal transmitted to the excitation end is received by the detection device. The control module calculates the time difference between the inquiry pulse and the received signal, and multiplies it by the propagation speed of torsional stress wave in the waveguide material, so as to calculate the distance between the torsional wave occurrence position and the measurement reference point, and realize the real-time accurate measurement of the vernier magnet position.



### Working principle of magnetostrictive linear displacement sensor

# RH/RP Displacement Sensor-Analog Output

### Technical Characteristics

- Rugged and fully enclosed design
- Non-wear, non-contact measurement method
- Easy to use, standard analog signal output
- No need to return to zero, absolute position output
- Easy diagnosis, LED real-time condition monitoring
- Low power consumption design effectively reduces system heating
- Stable and reliable, using digital analog technology
- The start and end position of the measurement can be adjusted in full scale

## C c Product Parameters-Analog Output

| • Input                 |  |
|-------------------------|--|
| Measurement data        | Position magnet ring   |
| Stroke length           | 25~5500 mm, customized according to customer needs   |
| Number of measurements  | 2  |
| Output                  |  |
| Current                 | 4 ~ 20mA or 20 ~ 4mA(min/max load 0/5002)  |
| Voltage                 | $0 \sim 10Vdc \text{ or } 0 \sim 5Vdc \pmod{(\min \text{ load resistance } \geq 10K)}$   |
| Resolution              | 16-bit D/A or 0.0015% of full scale (min 1um)  |
| Nonlinearity            | <±0.01% of full scale, min±50um  |
| Repetition accuracy     | <±0.001% of full scale, min ±1um   |
| Hysteresis              | <10um  |
| Update time             | Measuring range         ≤200mm         ≤350mm         ≤1200mm         ≤2400mm         ≤4800mm         ≤7620mm           Update time         0.25ms         0.333ms         0.5ms         1.0ms         2.0ms         5.0ms |
| Temperature coefficient | < <b>30ppm</b> / <sup>°</sup> C  |

| <ul> <li>Operating condition</li> </ul> | S   |
|---|---|
| Magnet velocity                         | Arbitrary   |
| Protection level                        | IP67 RH Stainless Stell Rod /IP65 RP Aluminum profile           |
| Operating temperature                   | -40°C ~ +85°C   |
| Humidity/dew point                      | Humidity 90%, no condensation                                   |
| Shock index                             | GB/T2423.5 100g(6ms)  |
| Vibration index                         | GB/T2423.10 20g/10~2000Hz                                       |
| EMC test                                | GB/T17626.2/3/4/6/8, Grade 4/3/4/3/3, Class A, CE Certification |

| • Str          | ucture and Mat        | terials  | • |
|----------------|-----------------------|--|---|
| F              | ailure indication     | Displayed by the LEDs on the rear cover of the electronic compartment      |   |
| Electronic bin |                       | Aluminum alloy   |   |
| BHC            | Measuring rod         | 304 stainless steel  |   |
| Series         | Outer tube pressure   | 35MPa (continuous) /70MPa (peak) or<br>350bar (continuous) / 700bar (peak) |   |
|                | Position magnet       | Standard magnet ring and various ring magnets                              |   |
| RPC            | Electronic bin        | Aluminum alloy   |   |
| Series         | Measuring rod         | Aluminum alloy   |   |
|                | Position magnet       | Slider magnet, square magnet, sector magnet                                |   |
| N              | lounting thread form  | M18×1.5、M20×1.5、3/4"-16UNF-3A<br>(customizable)                            |   |
| Ir             | nstallation direction | Any direction  |   |
| С              | outgoing mode         | Cable outlet or Connector  |   |

| Electrical Conne       | ections                     |
|------------------------|-----------------------------|
| Input voltage          | +24Vdc±20%                  |
| Operating current      | <120mA (varying with range) |
| Polarity protection    | Max30Vdc                    |
| Overvoltage protection | Max.36Vdc                   |
| Insulation resistance  | $> 10 M\Omega$              |
| Insulation strength    | 500V                        |

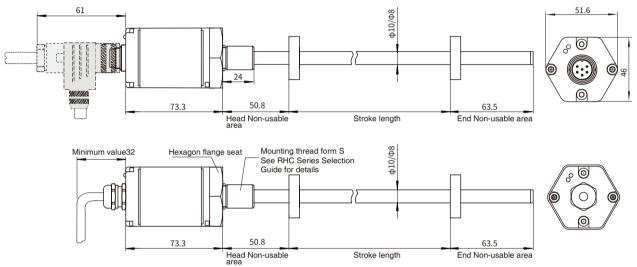
### A a Installation Instructions-Analog Output

Analog output magnetostrictive displacement sensor, suitable for real-time and precise measurement of moving parts stroke, it can measure the absolute displacement or stroke of vernier magnet, expressed in the form of standard analog quantity, including: 0~20MA (or reverse), 420MA (or reverse) DC current or 0~5V (or reverse),-5~+5V (or reverse), 0~10V (or reverse),-10~+10V (or reverse) DC voltage, etc. Sensors have built-in and external two different installation methods, built-in type is suitable for the built-in installation of hydraulic cylinders, compact structure; the external type adopts aluminum profile, which is installed outside the moving parts and convenient to use.

### Dimensions and installation guidance of RHC pressure-resistant rod sensor

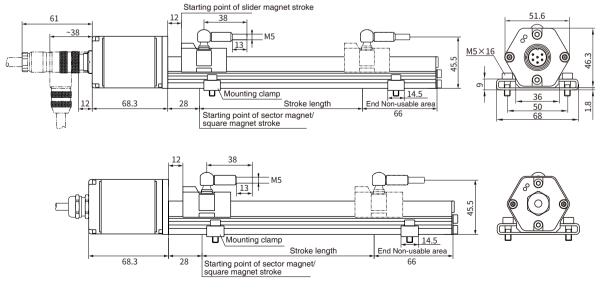
RH series pressure-resistant rodshell, built-in installation design for hydraulic system, pressure-resistant 35MPa continuous, flexible and simple installation mode.Mounting thread form M18×1.5 or M20×1.5 or 3/4"-16UNF-3A.

Note: The measurement Non-usable area shown in the figure indicates that the output value of the sensor in this area is zero or unreliable. The default values of the first and last measurement Non-usable areas of this product are 50.8mm and 63.5mm respectively. The value of the measurement Non-usable area can be appropriately modified according to the needs of customers, please pointed out when ordering.



Dimensions and installation guidance of RPC aluminum profile sensor

RPC Series aluminum profile provides flexible and simple external installation mode, which is suitable for stroke or position detection of linear motion mechanism, and can also be used for external position detection of hydraulic cylinder.



## **C** Common Accessories - Analog Output

| Accessory name/<br>model                  | Dimensions  | Accessory name/<br>model           | Dimensions                                   | Accessory name/<br>model                          | Dimensions   |
|---|---|------------------------------------|--|---|--------------|
| Standard magnet ring<br>Order No.: 211501 | Ф <u>33</u><br>4-Ф4.3<br>Ф <u>24</u><br>Ф <u>0</u><br>Ф <u>13.5</u><br>В<br>В | Magnetic isolation<br>gasket       | Ф33<br>4-Ф4.3<br>Ф <u>24</u><br>Ф <u>о</u> ф | 6-pin Female<br>Connector<br>Order No.: 312701    | 59<br>9<br>W |
| Sector magnet<br>Order No.: 211502        | 120°<br>2.04.3<br>R12<br>Φ13.5  | Sector magnetic isolation gasket   | 120°<br>2-04.3<br>B12<br>0-033<br>0-13.5     | 6-pin 90 Female<br>Connector<br>Order No.: 312702 |              |
| Slider magnet<br>Order No.: 211503        | 313<br>312<br>312<br>312<br>312<br>312<br>312<br>312<br>312<br>312            | Square magnet<br>Order No.: 211508 | 28<br>19<br>0<br>19<br>5<br>5<br>N           |   |              |

Note: Please refer to "Magnet ring Selection" for details of magnet ring kit and other models.

### • Wiring mode

When the sensor is a connector output, refer to the pin definition in the following table for wiring mode; when the sensor is cable outlet output, refer to the line color definition in the following table for connection mode





|     | in male co<br>Isor head) | nnector a        | rrangement (facing the  | •   | male conne<br>or head) | ector arrangement (facing the   |
|-----|--------------------------|------------------|---|-----|------------------------|---------------------------------|
| Pin | Line<br>color 1*         | Line<br>color 2* | Pin/wire function definition                                  | Pin | Line<br>color 3*       | Pin/wire function definition    |
| 1   | Blue                     | Grey             | No. 1 magnet ring position signal(+)                          | 1   | Yellow                 | Current output                  |
| 2   | Green                    | Pink             | No. 1 magnet ring position signal(-)                          | 2   | Grey                   | 0Vdc(Current/Voltage Loop)      |
| 3   | Yellow                   | Yellow           | No.2 magnet ring position (No.1 magnet ring speed) signal (+) | 3   | Pink                   | Voltage/current                 |
| 4   | White                    | Green            | No.2 magnet ring position (No.1 magnet ring speed) signal (-) | 4   | -                      | Reservation                     |
| 5   | Red                      | Brown            | +24Vdc power supply<br>(-20%~+20%)                            | 5   | Green                  | Voltage                         |
| 6   | Black                    | White            | 0 Vdc (power supply circuit)                                  | 6   | Blue                   | 0 Vdc (power supply circuit)    |
|     |                          |                  | PUR sheath, orange, -20~90 <sup>°</sup> C                     | 7   | Brown                  | +24Vdc power supply (-20%~+20%) |
|     | * Line colo              | r 2/3: cable     | e PVC sheath orange,-20~105℃                                  | 8   | White                  | Reservation                     |

## X X Selection Guide - Analog Output

#### 

16 - 19

Signal output mode

| 01 - 03       | 3 | Se | ensor shell form  |
|---------------|---|----|---|
| RH            | С | Pr | essure-resistant rod (internal or external)   |
| RP            | с | Al | uminum profile (external only)  |
| 04 - 08       | 2 | M  | easuring range  |
| 000           | , |    | pur-bit, less than four-bit are preceded by zero,                                   |
|               |   | М  | means metric system, unit mm  |
| 09 - 10       | ) | Ma | agnet ring type/mounting thread form  |
| Only for      | S | 1  | Hexagon flange type, M18 × 1.5, measuring rod<br>diameter 10mm, material of 304     |
| RHC<br>Series | S | 2  | Hexagon flange type, M20 $\times$ 1.5, measuring rod diameter 10mm, material of 304 |
|               | S | 3  | Hexagon flange type, 3/4 "-16UNF-3A,<br>measuring rod diameter 10mm, material 304   |
| Only for      | С | 1  | Sector magnet   |
| RPC           | С | 2  | Slider magnet ring  |
| Series        | С | 3  | Square magnet   |
| 11            |   | M  | echanical selection   |
| 0             |   |    | andard  |
| 10 10         |   |    |   |
| 12 - 15       |   |    | onnection form  |
| 12 - 13       | 3 |    | utgoing line type: straight-out cable mode  |
| DH            |   |    | JR sheath, orange,-20 ~ 90°C, end scattered,<br>ble color 1                         |
| DU            |   |    | /C sheath, orange,-20 ~ 105°C, end scattered, ble color 2                           |
| DB            |   |    | /C sheath, orange,-20 ~ 105°C, end scattered, ble color 3                           |
| DI            |   |    | JR sheath, orange,-20 ~ 90°C, end with 6-pin<br>nnector                             |
| DV            |   |    | /C sheath, orange,-20 ~ 105°C, end with 6-pin<br>nnector                            |
| DC            |   |    | /C sheath, orange,-20 ~ 105°C, end with 8-pin<br>nnector                            |
| 14 - 15       | 5 | Cá | able outlet mode: cable length, 01 ~ 99 meters                                      |
| 12 - 15       | 5 | С  | onnector form   |
| ΡH            | 6 | 0  | M16 male plug (6-pin)   |
| Note: Fee     |   |    | ing applies places refer to Appleg Cable  |

| 16   | Output  |
|--|---|
| А  | Current   |
| V  | Voltage   |
| 17   | Function  |
| 1  | Position (1 magnet, 1 output)   |
| 2  | Position (2 magnets, 2 outputs)   |
| 3  | Position and speed (1 magnet, 2 outputs)  |
| 4  | Position and rate (1 magnet, 2 outputs)   |
| 5  | Forward position and reverse position (1 magnet, 2 outputs)   |
| 6  | Position and internal temperature of electronic<br>compartment (1 magnet, 2 outputs)  |
| 7  | Displacement difference (2 magnets, 1 output)   |
| 18   | Output range  |
| 0  | 010VDC or 420mA   |
| 1  | 100VDC or 204mA   |
| 2  | 020mA   |
|  | 200mA   |
| 3  | 200IIIA   |
| 19   | Non-magnet ring state   |
|  |   |
| 19   | Non-magnet ring state   |
| 19<br>A  | Non-magnet ring state<br>Keep the original value  |
| 19<br>A<br>B   | Non-magnet ring state<br>Keep the original value<br>Maximum value   |
| 19<br>A<br>B<br>C  | Non-magnet ring state<br>Keep the original value<br>Maximum value<br>Minimum value  |
| 19<br>A<br>B<br>C<br>D   | Non-magnet ring state<br>Keep the original value<br>Maximum value<br>Minimum value<br>Customize   |
| 19<br>A<br>B<br>C<br>D<br>20   | Non-magnet ring state<br>Keep the original value<br>Maximum value<br>Minimum value<br>Customize<br>Options  |
| 19<br>A<br>B<br>C<br>D<br>20<br>0  | Non-magnet ring state         Keep the original value         Maximum value         Minimum value         Customize         Options         Standard  |
| 19<br>A<br>B<br>C<br>D<br>20<br>0<br>21 - 22                             | Non-magnet ring state         Keep the original value         Maximum value         Minimum value         Customize         Options         Standard         Non-usable area at head and end, customizable  |
| 19<br>A<br>B<br>C<br>D<br>20<br>0<br>21-22<br>S 0                        | Non-magnet ring state         Keep the original value         Maximum value         Minimum value         Customize         Options         Standard         Non-usable area at head and end, customizable         50.8mm+63.5mm  |
| 19<br>A<br>B<br>C<br>D<br>20<br>0<br>21-22<br>S<br>0<br>B<br>0           | Non-magnet ring state         Keep the original value         Maximum value         Minimum value         Customize         Options         Standard         Non-usable area at head and end, customizable         50.8mm+63.5mm         30mm+60mm  |
| 19<br>A<br>B<br>C<br>D<br>20<br>0<br>21-22<br>S<br>0<br>B<br>0<br>S<br>1 | Non-magnet ring state         Keep the original value         Maximum value         Minimum value         Customize         Options         Standard         Non-usable area at head and end, customizable         50.8mm+63.5mm         30mm+60mm         28mm+66mm (used in RPC series)         Maximum speed or rate value (optional: "function"   |
| 19<br>A<br>B<br>C<br>D<br>20<br>0<br>21-22<br>S<br>0<br>B<br>0<br>S<br>1 | Non-magnet ring state         Keep the original value         Maximum value         Minimum value         Customize         Options         Standard         Non-usable area at head and end, customizable         50.8mm+63.5mm         30mm+60mm         28mm+66mm (used in RPC series)         Maximum speed or rate value (optional: "function" is 3 or 4 is used)         The coding speed is in m/s, and the value is 0.01 to |

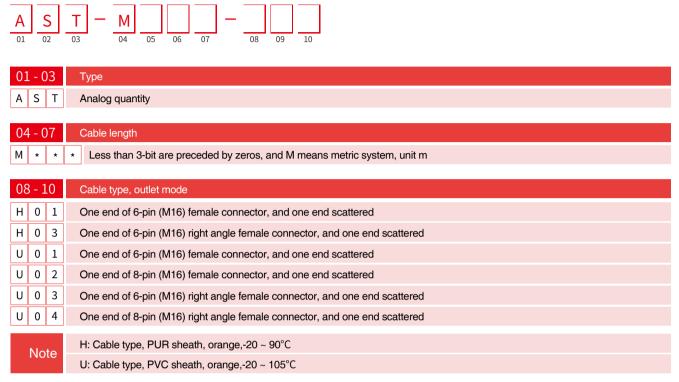
Note: For supporting cables, please refer to Analog Cable Accessories Selection

• Note: The forward output of the sensor means that when the magnet ring moves away from the electronic bin, the output value increases and decreases when the magnet ring moves in the reverse direction.

• Examples of selection: RHC-M0300-S10-PH60-A10B-S0

Indicates: the ordered product model is RHC structural displacement sensor, the measuring range is 300mm, and the mounting thread form is M18×1.5; the diameter of the measuring rod is 10mm, and the material is 304; 6-pin connector outlet form, without cable plug, 4-20mA output (1 magnet ring, 1 position output) the non-usable area of the first end is 50.8mm, and the non-usable area of the end is 63.5mm.

### M Selection of Analog Cable Fittings



Selection example: AST-M005-H01

Indicates: Analog interface cable, 5m long, PUR sheath, orange, -20~90°C, one end of the cable is a 6-pin (M16) right angle female connector, and one end scattered

Selection example: AST-M010-U04

Indicates: Analog interface cable, 10 meters long, PVC sheath, orange,-20 ~ 105°C, one end of the cable is a 8-pin (M16) right angle female connector, and one end scattered

# RHC/RPC Displacement Sensor -SSI Output



## CC Product Parameters - SSI Output

### • Input

| Measurement data       | Position magnet ring                               |
|------------------------|--|
| Stroke length          | 25~5500 mm, customized according to customer needs |
| Number of measurements | 2  |

### • Output

|   | Interface                            | SSI Synchronous Serial Interface   |  |  |  |              |                                    |
|---|--------------------------------------|--|--|--|--|--------------|------------------------------------|
|   | Data Format                          | Binary or Gray code  |  |  |  |              |                                    |
|   | Data length                          | 8~32bit  |  |  |  |              |                                    |
|   | Resolution                           | 0.1/0.5 / 1 / 2 / 5 / 10 / 20 / 40/ 50 / 100 µm  |  |  |  |              |                                    |
|   | Nonlinearity                         | <±0.01% of full scale, minimum ±50 $\mu$ m   |  |  |  |              |                                    |
|   | Repetition<br>accuracy               | $<\pm 0.001\%$ of full scale or the same resolution  |  |  |  |              |                                    |
|   | Transmission<br>rate                 | 50KBD~1MBD         line length       <3  |  |  |  |              |                                    |
|   | Update time<br>(High update<br>rate) | Stroke:         300         750         1000         2000         5000         mm           Frequency:         3.7         3.0         2.3         1.2         0.5         kHz |  |  |  |              |                                    |
|   | Update time<br>(general)             | 1KHz (range $\leq$ 1m) 500Hz (1m < range $\leq$ 2m)<br>250Hz (2m < range $\leq$ 3m), customizable  |  |  |  |              |                                    |
| Hysteresis <10µm<br>Temperature<br>coefficient <15ppm/ <sup>°</sup> C |                                      |  |  |  |  |              |                                    |
|   |                                      |  |  |  |  | Working mode | Asynchronous, Synchronous (Sync 1) |

Working mode Asynchronous, Synchronous (Sync 1)

### • Structure and Materials

| Failure indication      |                        | Electronic bin coverwith LEDs display                                 |  |  |
|-------------------------|------------------------|---|--|--|
|                         | Electronic bin         | Aluminum alloy  |  |  |
| RH<br>Series            | Measuring<br>rod       | 304 stainless steel   |  |  |
| Series                  | Outer tube<br>pressure | 35MPa (continuous)/70MPa (peak value)<br>(measuring rod diameter φ10) |  |  |
|                         | Position<br>magnet     | Standard magnet ring and various ring magnets                         |  |  |
|                         | Electronic<br>bin      | Aluminum alloy  |  |  |
| RP<br>Series            | Measuring<br>rod       | Aluminum alloy  |  |  |
|                         | Position<br>magnet     | Slider magnet, square magnet, sector magnet                           |  |  |
| Mounting thread<br>form |                        | M18×1.5、 M20×1.5、 3/4"-16UNF-3A<br>(customizable)                     |  |  |
| Install                 | ation direction        | Any direction, Threaded mounting (thread size optional)               |  |  |
| Outgoing mode           |                        | Cable outlet(Loose wire connection) or<br>Connector(M16)              |  |  |

| Operating conditions   |   |  |  |  |  |  |
|------------------------|---|--|--|--|--|--|
| Magnet<br>velocity     | Arbitrary   |  |  |  |  |  |
| Protection<br>level    | IP67RHC Stainless Stell Rod/IP65RPC<br>Aluminum profile           |  |  |  |  |  |
| Operating temperature  | <b>-40</b> °C ~ <b>+85</b> °C                                     |  |  |  |  |  |
| Humidity/<br>dew point | Humidity 90%, no condensation                                     |  |  |  |  |  |
| Shock index            | GB/T2423.5 100g(6ms)  |  |  |  |  |  |
| Vibration<br>index     | GB/T2423.10 15g/10~2000Hz   |  |  |  |  |  |
| EMC Test               | GB/T17626.2/3/4/6/8, Grade3/3/3/2/3,<br>Class A, CE Certification |  |  |  |  |  |

| Electrical Connections |                            |  |  |  |  |  |
|------------------------|----------------------------|--|--|--|--|--|
| Input voltage          | +24Vdc±20%                 |  |  |  |  |  |
| Operating current      | <80mA (varying with range) |  |  |  |  |  |
| Polarity protection    | Max30Vdc                   |  |  |  |  |  |
| Overvoltage protection | Max.36Vdc                  |  |  |  |  |  |
| Insulation resistance  | $> 10 M\Omega$             |  |  |  |  |  |
| Insulation strength    | 500V                       |  |  |  |  |  |

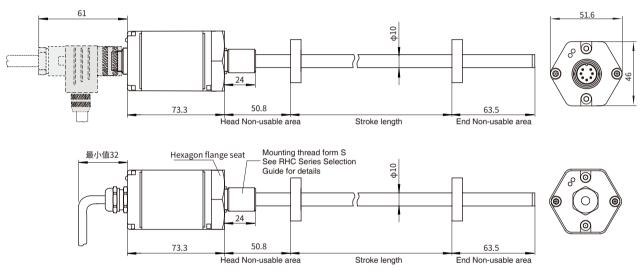
## A a Installation Instructions SSI Output

SSI output magnetostrictive linear displacement sensor provides synchronous serial signal output, which can convert the real-time position of vernier magnet into 24, 25 or 26-bit (binary or Gray code) data form, and transmit the data to the controller by serial communication after receiving the clock signal provided by the controller. The data format of SSI output is identical with absolute output encoder, and it can be connected directly with the function module of PLC, so it can be conveniently used to replace absolute encoder.

### • Dimensions and installation guidance of RHC pressure-resistant rod sensor

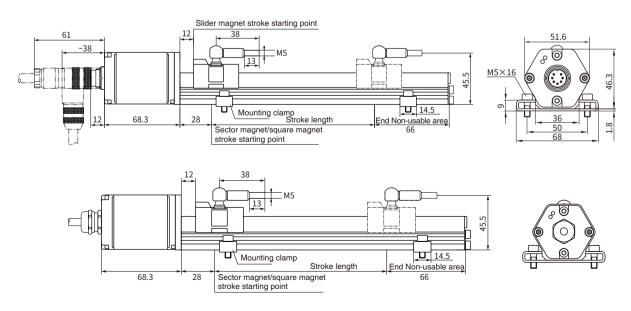
RHC series pressure-resistant rod shell, built-in installation design for hydraulic system, pressure-resistant 35MPa continuous, flexible and simple installation mode, mounting thread form M18×1.5 or M20×1.5 or 3/4" -16UNF-3A.

Note: The measurement non-usable area shown in the figure indicates that the output value of the sensor in this area is zero or unreliable. The default values of the first and last measurement non-usable areas of this product are 50.8mm and 63.5mm respectively. The value of the measurement non-usable area can be appropriately modified according to the needs of customers, please pointed out when ordering.



### • Dimensions and installation guidance of RPC aluminum profile sensor

RPC Series aluminum profile provides flexible and simple external installation mode, which is suitable for stroke or position detection of linear motion mechanism, and can also be used for external position detection of hydraulic cylinder.



## **C** Common Accessories - SSI Output

| Accessory name/<br>model                  | Dimensions   | Accessory name/<br>model           | Dimensions   | Accessory name/<br>model                          | Dimensions |
|---|--|------------------------------------|--|---|------------|
| Standard Magnet ring<br>Order No.: 211501 | 4-04.3<br>0-024<br>0-04<br>0-04<br>0-05<br>0-05<br>0-05<br>0-05<br>0-05<br>0-0 | Magnetic isolation<br>gasket       | 4 <u>−</u> 043<br>0 <u>−</u> 024<br>0 <u>−</u> 0<br>0 <u>−</u> − | 7-pinFemale<br>Connector<br>Order No.: 312703     | 9<br>W     |
| Sector magnet<br>Order No.: 211502        | 120°<br>R12<br>033<br>013.5  | Sector magnetic isolation gasket   | 120°<br><u>2:04.3</u><br><u>4033</u><br><u>413.5</u>             | 7-pin 90 Female<br>Connector<br>Order No.: 312704 | WIE<br>38  |
| Slider magnet<br>Order No.: 211503        | 33.5<br>37.5<br>M5<br>M5<br>M5   | Square magnet<br>Order No.: 211508 |  |   |            |

Note: Please refer to "Magnet ring Selection" for details of magnet ring kit and other models.

### • Wiring mode

When the sensor is connector output, refer to the pin definition in the following table for wiring mode; when the sensor is cable outlet output, refer to the line color definition in the following table for connection mode



|     | <ul> <li>7-pin male connector arrangement (facing the sensor head)</li> </ul> |                  |                                    |  |  |  |  |  |  |
|-----|---|------------------|------------------------------------|--|--|--|--|--|--|
| Pin | Line<br>color 1*  | Line<br>color 2* | Pin/wire function definition       |  |  |  |  |  |  |
| 1   | White   | Grey             | Data (-)                           |  |  |  |  |  |  |
| 2   | Yellow  | Pink             | Data (+)                           |  |  |  |  |  |  |
| 3   | Blue  | Yellow           | Clock (+)                          |  |  |  |  |  |  |
| 4   | Green   | Green            | Clock (-)                          |  |  |  |  |  |  |
| 5   | Red   | Brown            | +24Vdc power supply<br>(-20%~+20%) |  |  |  |  |  |  |
| 6   | Black   | White            | 0 Vdc                              |  |  |  |  |  |  |
| 7   | -   | -                | Do not connect                     |  |  |  |  |  |  |



| <ul> <li>8-pin male connector arrangement (facing the sensor head)</li> </ul> |                  |                                    |  |  |  |
|---|------------------|------------------------------------|--|--|--|
| Pin   | Line<br>color 3* | Pin/wire function definition       |  |  |  |
| 1   | Yellow           | Clock (+)                          |  |  |  |
| 2   | Grey             | Data (+)                           |  |  |  |
| 3   | Pink             | Clock (-)                          |  |  |  |
| 4   | -                | Reservation                        |  |  |  |
| 5   | Green            | Data (-)                           |  |  |  |
| 6   | Blue             | 0 Vdc (power supply circuit)       |  |  |  |
| 7   | Brown            | +24Vdc power supply<br>(-20%~+20%) |  |  |  |
| 8   | White            | Reservation                        |  |  |  |

Note: \* Line color 1: cable PUR sheath, orange, -20~90 °C \* Line color 2/3: Cable PVC sheath, orange,-20~105 °C

### **C** Selection Guide - SSI Output

# $\begin{bmatrix} \mathsf{R} \\ _{01} \end{bmatrix} \underbrace{\mathsf{C}} \\ _{02} \end{bmatrix} \underbrace{\mathsf{C}} \\ _{03} \end{bmatrix} \underbrace{\mathsf{M}} \\ _{04} \underbrace{\mathsf{M}} \\ _{05} \end{bmatrix} \underbrace{\mathsf{M}} \\ _{06} \underbrace{\mathsf{M}} \\ _{07} \underbrace{\mathsf{M}} \\ _{09} \underbrace{\mathsf{M}} \\ _{10} \underbrace{\mathsf{M}} \\ _{11} \underbrace{\mathsf{M}} \\ _{12} \underbrace{\mathsf{M}} \\ _{13} \underbrace{\mathsf{M}} \\ _{14} \underbrace{\mathsf{M}} \\ _{15} \underbrace{\mathsf{M}} \\ _{16} \underbrace{\mathsf{M}} \\ _{17} \underbrace{\mathsf{M}} \\ _{19} \underbrace{\mathsf{M}} \\ _{20} \underbrace{\mathsf{M}} \\ _{21} \underbrace{\mathsf{M}} \\ _{22} \underbrace{\mathsf{M}} \\ _{23} \underbrace{\mathsf{M}} \\ _{24} \underbrace{\mathsf{M}} \\ _{25} \underbrace{\mathsf{M}} \\ _{25} \underbrace{\mathsf{M}} \\ _{26} \underbrace{\mathsf{M}} \\ _{26} \underbrace{\mathsf{M}} \\ _{21} \underbrace{\mathsf{M}} \\ _{21} \underbrace{\mathsf{M}} \\ _{22} \underbrace{\mathsf{M}} \\ _{22} \underbrace{\mathsf{M}} \\ _{22} \underbrace{\mathsf{M}} \\ _{23} \underbrace{\mathsf{M}} \\ _{24} \underbrace{\mathsf{M}} \\ _{25} \underbrace{\mathsf{M}} \\ _{26} \underbrace{\mathsf{M} \\ _{26} \underbrace{\mathsf{M}} \\ _{26} \underbrace{\mathsf{M}$

| 01 - 03                 | 3                              | Se  | ensor shell form   | 15 | 5 - 2 | 22       | S               | ignal output      | t mode  | 9                |         |        |                      |
|-------------------------|--------------------------------|---|--|----|-------|----------|-----------------|-------------------|---------|------------------|---------|--------|----------------------|
| R H                     | С                              | Pressure-resistant rod (internal or external)                       |  |    | 15    |          | S               | SS1               |         |                  |         |        |                      |
| R P                     | С                              | C Aluminum molded shell (external only)                             |  |    | 16    |          | 1               | 1 Position        |         |                  |         |        |                      |
| 04 - 08 Measuring range |                                |   | 17   |    | 0     | Standard | b               |                   |         |                  |         |        |                      |
|                         |                                | Fc  | pur-bit, less than four-bit are preceded by zero,                    |    | 18    |          | D               | ata length        |         |                  |         |        |                      |
|                         |                                | М   | means metric system, unit mm   |    |       | 1        | 24bit 2 25bit 3 |                   |         | ;                | 26bit * |        |                      |
| 09 - 10                 | )                              | Ma  | agnet ring type/mounting thread form                                 |    |       |          | *               | 26-bit are p      | arity b | its and 25-bit a | are sta | atus b | its                  |
|                         | S                              | 1   | M 18 $\times$ 1. 5, measuring rod diameter 10mm, 304 material        |    | 19    |          | D               | ata format        |         |                  |         |        |                      |
|                         | S                              | 2   | M20 $\times$ 1. 5, measuring rod diameter 10mm, 304 material         |    | 20    | В        |                 | inary             | G       | Gray code        |         |        |                      |
| Only for<br>RHC         | S                              | 3   | 3/4 "-16UNF-3A, measuring rod diameter 10mm. 304 material            |    | 20    | 1        |                 | esolution<br>.1mm | 2       | 0.05mm           |         |        |                      |
| Series                  | Т                              | 1   | M18X1.5, measuring rod diameter 8mm,<br>304 material                 |    |       | 3        | 0.              | .02mm             | 4       | 0.01mm           |         |        |                      |
|                         | Т                              | 2   | M20X1.5, measuring rod diameter 8mm,                                 |    |       | 5        | 0.              | .005mm            | 6       | 0.002mm          |         |        |                      |
|                         | Т                              | 3   | 304 material<br>3/4 "-16UNF-3A, measuring rod diameter 8mm,          |    |       | 7<br>9   |                 | .001mm            | 8       | 0.04mm           |         |        |                      |
|                         |                                |   | 304 material   |    | 21    | 9        |                 | .0005mm           | 0       | 0.0001mm         |         |        |                      |
| Only for                | С                              | 1   | Sector magnet  |    | 21    | 0        |                 | irection          | 1       | Deverse          |         |        |                      |
| RPC<br>Series           | С                              | 2   | Slider magnet ring   |    |       | 0        |                 | orward            | 1       | Reverse          |         |        |                      |
| 001100                  | С                              | 3   | Square magnet  |    | 22    |          |                 | nodel             |         | Synchroni-       |         | Lliab  | ****                 |
| 11 - 14                 | 1                              | Co  | onnection form   |    |       | 0        | asyr            | nchronous         |         | zation 1         | 2       | async  | response<br>chronous |
| 11-12                   |                                | 0ι  | utgoing line type: straight-out cable mode                           | 23 | 3 - 2 | 24       | N               | on-usable a       | area a  | t head and end   | d, cus  | tomiz  | able                 |
| DH                      |                                |   | JR sheath, orange,-20 ~ 90°C, end scattered,<br>ble color 1          | S  | 0     |          | 5               | 0.8mm+63.         | 5mm     |                  |         |        |                      |
| DU                      |                                |   | /C sheath, orange, -20~105°C, loose wire at the<br>id, cable color 2 | В  | 0     |          | -               | 0mm+60mr          |         |                  |         |        |                      |
| DB                      |                                | PVC sheath, orange,-20 ~ 105°C, end scattered,                      |  | S  | 1     |          | 2               | 8mm+66mr          | n (use  | d in RPC serie   | es)     |        |                      |
| DI                      |                                | cable color 3<br>PUR sheath, orange,-20 ~ 90°C, end 7-pin connector |  | 25 | 5-20  | 5<br>1   |                 | ountry            |         |                  | 00      |        |                      |
| DV                      |                                | PVC sheath, orange,-20 ~ 105°C, end 7-pin connector                 |  |    |       |          | ŀ               | Refer to the      | coun    | try list, page   | 23.     |        |                      |
| DC                      |                                | PVC sheath, orange,-20 ~ 105°C, end 8-pin connector                 |  |    |       |          |                 |                   |         |                  |         |        |                      |
| 13 - 14                 | 1                              | Cable outlet mode: cable length, 01 ~ 99 meters                     |  |    |       |          |                 |                   |         |                  |         |        |                      |
| 11 - 14                 | 11 - 14 Connector form         |   |  |    |       |          |                 |                   |         |                  |         |        |                      |
| ΡΗ                      | P H 7 0 M16 male plug (7 pins) |   |  |    |       |          |                 |                   |         |                  |         |        |                      |

Note: See SSI cable fittings selection for supporting cables

• Note: The forward output of the sensor means that when the magnet ring moves away from the electronic bin, the output value increases and decreases when the magnet ring moves in the reverse direction.

Selection example: RHC-M0300-S1-PH70-S101B700-S0

Indicates: R H C rod structure series, 3 0 mm effective stroke, M 18 X 1. 5 mounting thread, measuring rod diameter 1 0 mm, 3 0 4 material, connector outlet form, no cable plug, S S I protocol output (position output, data length 2 4 bits, data format binary, resolution 0. 0 0 1 mm, forward output, asynchronous mode), head non-usable area 5 0. 8 mm, end non-usable area 6 3. 5 mm.

## S SSI Cable accessories selection Guide



| 01-03   | Туре  |  |  |  |  |  |  |  |  |
|---------|---|--|--|--|--|--|--|--|--|
| S S I   | SSI interface   |  |  |  |  |  |  |  |  |
| 04 07   |   |  |  |  |  |  |  |  |  |
| 04 - 07 | 04 - 07 Cable length  |  |  |  |  |  |  |  |  |
| M * *   | * Less than 3 digits are preceded by zeros, and M means metric system, unit m |  |  |  |  |  |  |  |  |
|         |   |  |  |  |  |  |  |  |  |
| 08 - 10 | Cable type, outlet mode   |  |  |  |  |  |  |  |  |
| H 0 1   | One end of 7-pin (M16) is female connector, and one end scattered             |  |  |  |  |  |  |  |  |
| H 0 3   | One end of 7-pin (M16) right angle female connector, and one end scattered    |  |  |  |  |  |  |  |  |
| U 0 1   | One end of 7-pin (M16) is female connector, and one end scattered             |  |  |  |  |  |  |  |  |
| U 0 2   | One end of 8-pin (M16) is female connector, and one end scattered             |  |  |  |  |  |  |  |  |
| U 0 3   | One end of 7-pin (M16) right angle female connector, and one end scattered    |  |  |  |  |  |  |  |  |
| U 0 4   | One end of 8-pin (M16) right angle female connector, and one end scattered    |  |  |  |  |  |  |  |  |
|         | H: Cable type, PURsheath, orange, -20~90 C                                    |  |  |  |  |  |  |  |  |
| Note    | U: Cable type, PVC sheath, orange,-20~105°C                                   |  |  |  |  |  |  |  |  |

• Selection example: SSI-M005-H01

Indicates: SSI interface cable, cable length 5 meters, PURsheath, orange, -20~90 $^{\circ}$ , one end of the cable is 7-pin (M16) female connector, and one end scattered.

• Selection example: SSI-M010-U04

Indicates: SSI interface cable, cable length 10 meters, PVC sheath, orange, -20~105 $^{\circ}$ , one end of the cable is an 8-pin (M16) right angle female connector, and one end scattered.

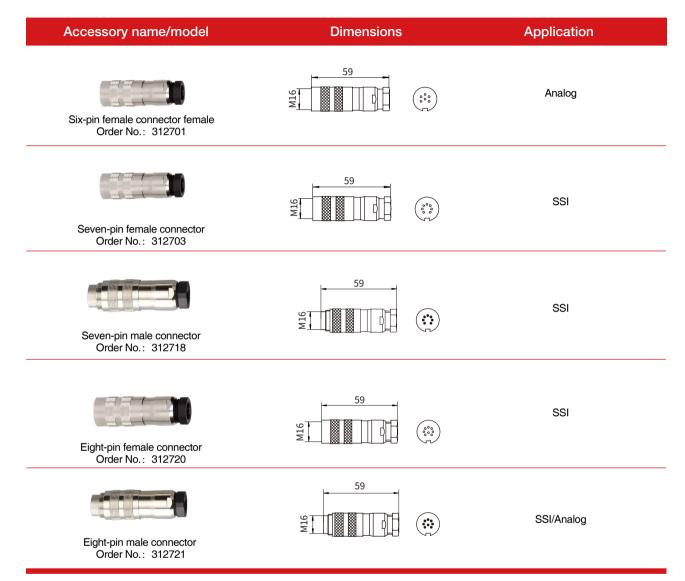
# **Magnet ring Selection**

| Accessory name/model                                | Dimensions   | Description/application  |
|---|--|--|
| Standard magnet ring Kit<br>Order No.: 288501       | $\begin{array}{c} \underline{\phi_{33}} \\ \underline{4 \cdot \phi_{4,3}} \\ \underline{\phi_{24}} \\ \phi_{2$ | Magnetic insulation gasket: size same as<br>magnet ring, thickness 5mm<br>Screw: GB/T70.1, M4X18, Material 304<br>Spring gasket: GB/T 93, Φ 4,<br>Material304<br>Includes: 1 Magnet, 1 gasket, 4 screws<br>with spring washer<br>Application: RHC/RF/FBGB/RS/RD/RB |
| Sector magnet kit<br>Order No.: 288502              | 120°<br><u>2-Ф4.3</u><br><u>433</u><br><u>412</u><br><u>413.5</u>  | Magnetic insulation gasket: size same as magnet ring, thickness 5mm Screw: GB/T70.1, M4X18, Material 304 Spring gasket: GB/T 93, $\Phi$ 4, Material 304 Includes: 1 Magnet, 1 gasket, 2 screws with spring washer Application: RPC                                 |
| Weak magnet Magnet ring 32 kit<br>Order No.: 288519 | Ф32.5<br>Ф13.5<br>2-Ф4<br>22.5   | Magnetic insulation gasket: size same as<br>magnet ring, thickness 5mm<br>Screw: GB/T70.1, M4X20, Material 304<br>Spring gasket: GB/T93, Φ4, material 304<br>Includes: 1 Magnet, 1 gasket, 2 screws with<br>spring washer<br>Application: RHC/RF/FBGB/RS/RD/RB     |

# **Cable Selection**

| Accessory name/model Dimensions                         |   | Application   |  |  |
|---|---|---|--|--|
| Standard Cable (H)<br>Order No.: 511802                 | 3P×0.25mm <sup>2</sup> ; Ф7.2mm<br>Conductor: 6-core, red/black, blue/green,<br>yellow/white<br>Sheath: Orange, PUR<br>Shielding layer: tinned copper wire mesh +<br>aluminum foil<br>Application characteristics: soft, oil resistance<br>and bending resistance<br>Temperature: (-20~90℃)   | Interface: Analog/SSI<br>Interface/Start/Stop<br>Structure: RHC/RPC/RF/FBGB<br>RS/RB/RD |  |  |
| Orange European Standard Cable (U)<br>Order No.: 511807 | $7 \times 0.25 \text{mm}^2$ ; $\Phi 7 \text{mm}$<br>Conductor:7-core,white/brown/green/yel-<br>low/gray/pink/blue<br>Sheath: Orange, modified PVC<br>Shielding layer: tinned copper wire mesh +<br>aluminum foil<br>Application characteristics: Extremely soft, oil<br>resistance, bending resistance, high temperature<br>resistance compliant with European colour code<br>Temperature: $(-20 \sim 105 \text{ C})$ | Interface: Analog/SSI<br>Interface/Start/Stop<br>Structure: RHC/RPC/RF/FBGB<br>RS/RB/RD |  |  |

## **Connector Selection**



Note: Please contact other accessories such as magnet rings, connectors and cables of other specifications!

## **Industrial Application**



Metallurgical industry



Port machinery



Hydraulic machinery



Wind power industry



Injection molding machinery



**Vulcanizing machinery** 



Die casting machinery



Vertical mill machinery



**Construction machinery** 



Papermaking machinery



Liquid level tank



Forming machinery

## **Country list**

AF - Afghanistan 阿富汗 AL - Albania 阿尔巴尼亚 DZ - Algeria 阿尔及利亚 AS - American Samoa 东萨摩亚 AD - Andorra 安道尔 AO - Angola 安哥拉 Av - Anguilla 安圭拉岛 AQ - Antarctica 南极洲 AG - Antigua and Barbuda 安提瓜和巴布达 AR - Argentina 阿根廷 AM - Armenia 亚美尼亚 AA - Aruba 阿鲁巴 AU - Australia 澳大利亚 AT - Austria 奥地利 AZ - Azerbaijan 阿塞拜疆 BF - Bahamas 巴哈马 BH - Bahrain 巴林 BB - Barbados 巴巴多斯 BD - Bangladesh 孟加拉 BY - Belarus 白俄罗斯 BE - Belgium 比利时 BZ - Belize 伯里兹 BJ - Benin 贝宁 BM - Bermuda 百慕大 BS - Bahamas 巴哈马 BT - Bhutan 不丹 BW - Botswana 博茨瓦纳 BO - Bolivia 玻利维亚 BA - Bosnia and Herzegovina 波黑 BV - Bouvet Island 布韦岛 BR - Brazil 巴西 IO - British Indian Ocean Territory 英属印度 洋领地 BN - Brunei Darussalam 文莱布鲁萨兰 BG - Bulgaria 保加利亚 BF - Burkina Faso 布基纳法索 BI - Burundi 布隆迪 KH - Cambodia (Internet) 柬埔寨 CB - Cambodia (CIA World Fact Book) 柬埔 寨 CM - Cameroon 喀麦隆 CA - Canada 加拿大

CV - Cape Verde 佛得角 KY - Cayman Islands 开曼群岛 CF - Central African Republic 中非 TD - Chad 乍得 CL - Chile 智利 CN - China 中国 CX - Christmas Island 圣诞岛 CC - Cocos (Keeling) Islands 可可斯群岛 CO - Colombia 哥伦比亚 KM - Comoros 科摩罗 CG - Congo 刚果 CD - Congo, Democratic Republic 刚果 CK - Cook Islands 库克群岛 CR - Costa Rica 哥斯达黎加 CI - Cote Divoire (Ivory Coast) 象牙海岸 HR - Croatia (Hrvatska) 克罗地亚 CU - Cuba 古巴 CY - Cyprus 塞普路斯 CZ - Czech Republic 捷克 CS - Czechoslovakia (former) 捷克斯洛伐 克 DK - Denmark 丹麦 DJ - Djibouti 吉布提 DM - Dominica 多米尼加共和国 DO - Dominican Republic 多米尼加联邦 TP - East Timor 东帝汶 EC - Ecuador 厄瓜多尔 EG - Egypt 埃及 SV - El Salvador 萨尔瓦多 GQ - Equatorial Guinea 赤道几内亚 ER - Eritrea EE - Estonia 爱沙尼亚 ET - Ethiopia 埃塞俄比亚 FK - Falkland Islands (Malvinas) 福兰克群岛 FO - Faroe Islands 法罗群岛 FJ - Fiii 斐济 FI - Finland 芬兰 FR - France 法国 FX - France, Metropolitan GF - French Guiana 法属圭亚那 PF - French Polynesia 法属玻里尼西亚

TF - French Southern Territories 法国南部 领地 MK - F.Y.R.O.M. (Macedonia) GA - Gabon 加蓬 GM - Gambia 冈比亚 GE - Georgia 格鲁吉亚 DE - Germany 德国 GH - Ghana 加纳 GI - Gibraltar 直布罗陀 GB - Great Britain (UK) 英国 GR - Greece 希腊 GL - Greenland 格陵兰岛 GD - Grenada 格林纳达 GP - Guadeloupe 法属德洛普群岛 GU - Guam 关岛 GT - Guatemala 危地马拉 GN - Guinea 几内亚 GW - Guinea-Bissau 几内亚比绍 GY - Guyana 圭亚那 HT - Haiti 海地 HM - Heard and McDonald Islands 赫德和 麦克唐纳群岛 HN - Honduras 洪都拉斯 HK - Hong Kong 中国香港特区 HU - Hungary 匈牙利 IS - Iceland 冰岛 IN - India 印度 ID - Indonesia 印度尼西亚 IR - Iran 伊朗 IQ - Iraq 伊拉克 IE - Ireland 爱尔兰 IL - Israel 以色列 IT - Italy 意大利 JM - Jamaica 牙买加 JP - Japan 日本 JO - Jordan 约旦 KZ - Kazakhstan 哈萨克斯坦 KE - Kenya 肯尼亚 KI - Kiribati 基里巴斯

KR - Korea (South) 韩国 KW - Kuwait 科威特 KG - Kyrgyzstan 吉尔吉斯斯坦 LA - Laos 老挝 LV - Latvia 拉托维亚 LB - Lebanon 黎巴嫩 LI - Liechtenstein 列支顿士登 LR - Liberia 利比里亚 LY - Libya 利比亚 LS - Lesotho 莱索托 LT - Lithuania 立陶宛 LU - Luxembourg 卢森堡 MO - Macau 中国澳门特区 MG - Madagascar 马达加斯加 MW - Malawi 马拉维 MY - Malaysia 马来西亚 MV - Maldives 马尔代夫 ML - Mali 马里 MT - Malta 马耳他 MH - Marshall Islands 马绍尔群岛 MQ - Martinique 法属马提尼克群岛 MR - Mauritania 毛里塔尼亚 MU - Mauritius 毛里求斯 YT - Mayotte MX - Mexico 墨西哥 FM - Micronesia 米克罗尼西亚 MC - Monaco 摩纳哥 MD - Moldova 摩尔多瓦 MA - Morocco 摩洛哥 MN - Mongolia 蒙古 MS - Montserrat 蒙塞拉特岛 MZ - Mozambique 莫桑比克 MM - Myanmar 缅甸 NA - Namibia 纳米比亚 NR - Nauru 瑙鲁 NP - Nepal 尼泊尔 NL - Netherlands 荷兰 AN - Netherlands Antilles 荷属安德列斯 NT - Neutral Zone 中立区(沙特-伊拉克间) NC - New Caledonia 新卡里多尼亚

KP - Korea (North) 朝鲜

NZ - New Zealand (Aotearoa) 新西兰 NI - Nicaragua 尼加拉瓜 NE - Niger 尼日尔 NG - Nigeria 尼日利亚 NU - Niue 纽爱 NF - Norfolk Island 诺福克岛 MP - Northern Mariana Islands 北马里亚纳 群岛 NO - Norway 挪威 OM - Oman 阿曼 PK - Pakistan 巴基斯坦 PW - Palau 帕劳 PA - Panama 巴拿马 PG - Papua New Guinea 巴布亚新几内亚 PY - Paraguay 巴拉圭 PE - Peru 秘鲁 PH - Philippines 菲律宾 PN - Pitcairn 皮特克恩岛 PL - Poland 波兰 PT - Portugal 葡萄牙 PR - Puerto Rico 波多黎各 QA - Qatar 卡塔尔 RE - Reunion 法属尼留旺岛 RO - Romania 罗马尼亚 RU - Russian Federation 俄罗斯 RW - Rwanda 卢旺达 GS - S. Georgia and S. Sandwich Isls. KN - Saint Kitts and Nevis 圣基茨和尼维斯 LC - Saint Lucia 圣卢西亚 VC - Saint Vincent and the Grenadines 圣文 森特和格陵纳丁斯 WS - Samoa 西萨摩亚 SM - San Marino 圣马力诺 ST - Sao Tome and Principe 圣多美和普林 西比. SA - Saudi Arabia 沙特阿拉伯 SN - Senegal 塞内加尔 SC - Seychelles 塞舌尔 SL - Sierra Leone 塞拉利昂

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SU - USSR (former) 前苏联

UZ - Uzbekistan 乌兹别克斯坦

VU - Vanuatu 瓦努阿鲁 VA - Vatican City State (Holy See) 梵蒂岗 VE - Venezuela 委内瑞拉 VN - Viet Nam 越南 VG - Virgin Islands (British) 英属维京群岛 VI - Virgin Islands (U.S.) 美属维京群岛

WF - Wallis and Futuna Islands 瓦里斯和福 图纳群岛 EH - Western Sahara 西撒哈拉

YE - Yemen 也门 YU - Yugoslavia 南斯拉夫

ZM - Zambia 赞比亚 (ZR - Zaire) - See CD Congo, Democratic Republic 扎伊尔 ZW - Zimbabwe 津巴布韦

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